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Question :- (a) State and Explain the (basic) fundamental postulates of the special theory of relativity.

(b) A reference frame  $S$  moves w.r. to another frame  $S'$  with uniform velocity  $\vec{v}$ . Derive Lorentz space and Time Transformation eq<sup>n</sup> gives  $x', y', z', t'$  in terms of  $x, y, z, t$  the moving frame coincides with stationary ones at  $t'=t=0$ . Prove that when  $\vec{v}$  is much smaller than velocity of light Lorentz Transformation reduce to Galilean Transformations.

Ans :- (a) Special theory of relativity :-

The special theory of relativity was enunciated in 1905 by Albert-Einstein. It has two fundamental postulates :-

① The laws of physics are invariant in all inertial systems :- An inertial system is defined as a co-ordinate frame of reference within which the law of inertia, i.e. Newton's first law of motion holds. A body on which no net external force acts will move with a uniform velocity, if it is in an inertial system. Hence according to this postulates the mathematical form of physical law remains the same for any two observers moving with constant linear velocity relative to each other. It is therefore, not possible to distinguish one inertial system from another by an experiment in physics, As the laws of physics are the same for an inertial frame. In other words there is no preferred inertial system.

② The speed of light in vacuum is a constant independent of the inertial system, the source and the observer. In other words, the velocity of light is an invariant.

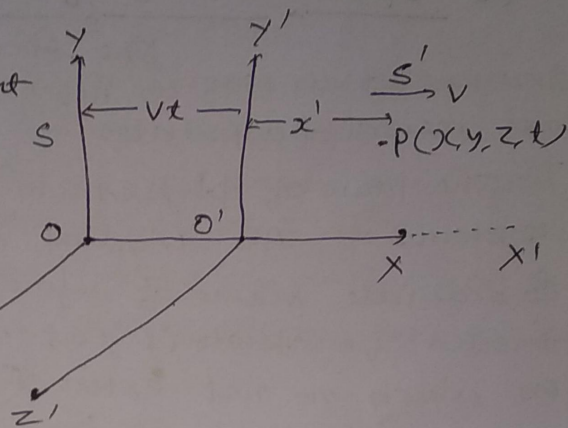
(b) Lorentz Transformation :-

The eq<sup>n</sup> in relativity physics, which relate the space and time co-ordinates of two co-ordinate

Systems moving with a uniform velocity relative to one another are called Lorentz transformation. (2)

Consider two observers  $O$  and  $O'$  located in two separate inertial co-ordinate systems  $S$  and  $S'$ . The system  $S'$  moves with a uniform velocity  $v$  to the right along the  $x$ -axis relative to  $S$ . This is equivalent to the motion of  $S$  to the left with a velocity  $v$  relative to  $S'$ . Suppose each observer carries a metre rod and a clock to measure the position and time of a particle relative to an inertial system. By specifying the position and time of a physical phenomenon, the observer describes what is called an event.

The space and time co-ordinates of an event at  $P$  described by an observer  $O$  are  $(x, y, z, t)$  and the co-ordinates of the  $x, y, z$  give the distance from the origin  $O$  along the  $x, y$  &  $z$  directions as measured by the meter stick of the observer  $O$  and  $t$  gives the time



that he reads on his clock. Suppose both the observers are temporarily at rest w.r. to each other when they compare their metre sticks and synchronise their clocks. The system  $S'$  is then set in motion w.r. to system  $S$ . When the origin of  $S'$  passes the origin of  $S$  both the clocks read zero, i.e.  $t=0$  and  $t'=0$  and at that instant  $x=x'$ .

It is evident that after time  $t$  as measured by  $O$ , the origin of the system  $S'$  is at distance  $vt$  from the origin of the space  $S$ .

$$\therefore x' = x - vt$$

As the relative motion between  $S'$  and  $S$  is at right angle to  $y$  and  $z$  axes, the position co-ordinate

$$y' = y \text{ and } z' = z$$

Further according to classical physics

(3)

the two observers  $O$  and  $O'$  will compute the same time for any signal originating from  $P$  after giving allowance for the velocity of  $S'$

$$\therefore t' = t$$

Hence non relativistic Galilean Transformation eq<sup>n</sup> are -  
 $x' = x - vt$ ,  $y' = y$ ,  $z' = z$ ,  $t' = t$

Lorentz Transformation eq<sup>n</sup> which satisfy the relativity requirements according to the two postulates must also be linear and not quadratic or of a higher order. A quadratic equation has two roots and a higher order equation even more. In order that an event  $(x, y, z, t)$  in the inertial system  $S$  may correspond to a single event  $(x', y', z', t')$  in the inertial system  $S'$  and vice-versa, there must be a one to one correspondance and the transformation equations must be linear in space co-ordinates as well as in time coordinates.

As the inertial system  $S'$  is moving with respect to the inertial system  $S$  along the  $x$ -direction, A ray of light parallel to the  $x$ -axis remains always parallel to  $x'$ -axis

$$y = y' \text{ and } z = z'$$

Hence  $x$  and  $t$  will both depend on  $x'$  and  $t'$ .

We shall therefore assume the simplest linear equation for Lorentz transformation, i.e

$$x = Ax' + Bt', \quad y = y', \quad z = z' \text{ and } t = Gx' + Ht'$$

It has been assumed in the above eq<sup>n</sup> that it is possible that the time interval for the two observer  $O$  and  $O'$  in the inertial system  $S$  and  $S'$  may not be identical

Imagine that at time  $t = t' = 0$ , when the origin  $O'$  coincides with the origin  $O$  a spherical pulse of light leaves the common origin of  $S$  and  $S'$ . As the velocity of light is invariant each observer sees a spherical wave expanding outwards with the speed  $c$  in his own system as measured by his own meters stick and clock.

$$\therefore \text{For the observer } O \text{ in system } S \quad c = \sqrt{x^2 + y^2 + z^2} / t$$

$$\text{or } x^2 + y^2 + z^2 = c^2 t^2 \Rightarrow x^2 + y^2 + z^2 - c^2 t^2 = 0 \quad \text{--- (1)}$$

Similarly for observer O' in system S',  $c = \sqrt{x'^2 + y'^2 + z'^2} / t'$  (11)

$$\therefore x'^2 + y'^2 + z'^2 - c^2 t'^2 = 0$$

from (1) and (11)  $x^2 + y^2 + z^2 - c^2 t^2 = x'^2 + y'^2 + z'^2 - c^2 t'^2$ ,  $y = y'$  &  $z = z'$

$$\therefore x^2 - c^2 t^2 = x'^2 - c^2 t'^2$$

Substituting  $x = Ax' + Bt'$  and  $t = Gx' + Ht'$  we get

$$(Ax' + Bt')^2 - c^2(Gx' + Ht')^2 = x'^2 - c^2 t'^2$$

Comparing co-efficients on both sides we have (11)

$$x'^2 [A^2 - c^2 G^2] = x'^2 \text{ or } A^2 - c^2 G^2 = 1 \text{ (12)}$$

$$t'^2 [B^2 - c^2 H^2] = -c^2 t'^2 \text{ or } B^2 - c^2 H^2 = -c^2 \text{ (13)}$$

$$\& 2x't' [AB - c^2 GH] = 0 \text{ or } AB - c^2 GH = 0 \text{ (14)}$$

Now when  $x' = 0$ ,  $x = vt$

$\therefore x = Ax' + Bt'$  and  $t = Gx' + Ht'$ , we get  $vt = Bt'$  &  $t = Ht'$

$$\therefore vHt' = Bt' \therefore B = vH$$

from (13)  $v^2 H^2 - c^2 H^2 = -c^2$  or  $H^2 = \frac{c^2}{c^2 - v^2} \therefore H = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$

Substituting this value of H in  $B = vH$ , we get  $B = \frac{v}{\sqrt{1 - \frac{v^2}{c^2}}}$

from (12)  $B = vH$  (we get)

$$AvH - c^2 GH = 0 \text{ or } Av = c^2 G \therefore G = \frac{Av}{c^2}$$

Substituting  $G = Av/c^2$  in eqn (12)

$$A^2 - A^2 \frac{v^2}{c^2} = 1 \therefore A = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\text{Hence } G = \frac{v/c^2}{\sqrt{1 - v^2/c^2}}$$

Substituting these values of A, B, G & H, the Lorentz transformation are

$$x = \frac{x' + vt'}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$t = t' + \frac{v}{c^2} \frac{x'}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$y = y' \text{ and}$$

$$z = z'$$